

1. With  $S^2 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$ , let  $f : S^2 \rightarrow S^2$  by  $f(\mathbf{x}) = -\mathbf{x}$  be the antipodal map. Let  $(X, Y)$  be stereographic projection coordinates from the north pole  $(0, 0, 1)$ . For  $p \in S^2$ , find  $T_p f(\frac{\partial}{\partial X})$  and  $T_p f(\frac{\partial}{\partial Y})$ .

- Lee, Chapter 2, problem 2. The hint refers to Theorem 2.25, the Inverse Mapping Theorem for manifolds.
- Lee, Chapter 2, problem 12. The problem needs some clarification, because it's not clear what sort of structure the set  $N$  comes with. At least, you should find a bijection  $f : TS^n \rightarrow N$ . Better, you want  $f$  to be a smooth map into  $\mathbb{R}^{2n+2}$ . Even better, you could show  $f$  is an immersion, as defined in Chapter 3 (which amounts to showing that  $Tf$  has rank  $2n$ ). Finally, you might also ask that  $f$  respect the vector space structures. For  $x \in \mathbb{R}^{n+1}$ , the set  $V_x = \{y \in \mathbb{R}^{n+1} \mid (x, y) \in N\}$  is a vector space, and  $f$  should be a linear isomorphism from  $T_p S^n$  to  $V_{f(p)}$  for each  $p \in S^n$ .

The main point of this problem was simply define a map  $f$  that has all these properties. Probably you should show it is smooth. Then, prove as much of the rest as you wish.

- Lee, Chapter 2, problem 20.